Know Your Lidar Data

Assessing the Accuracy/Quality
Integrating Other Sources of Data
Extracting Information and Features From
Lidar Data

Karen Kwasnowski

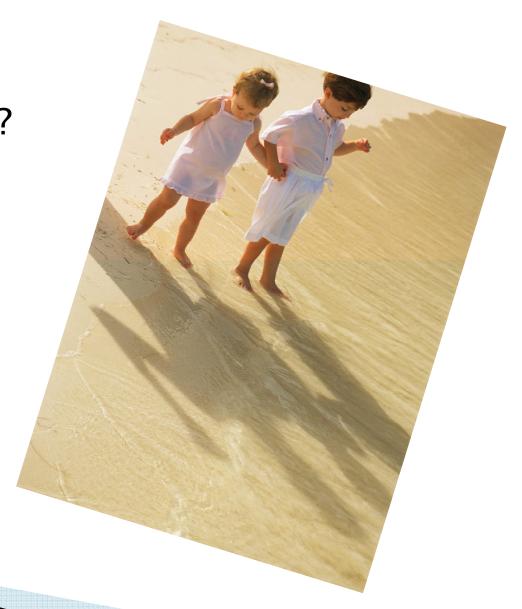


Today's Topics

- What does Lidar data look like?
- Errors in the Lidar data
- Integrating other datasets in with the Lidar
- Extracting Information from Lidar

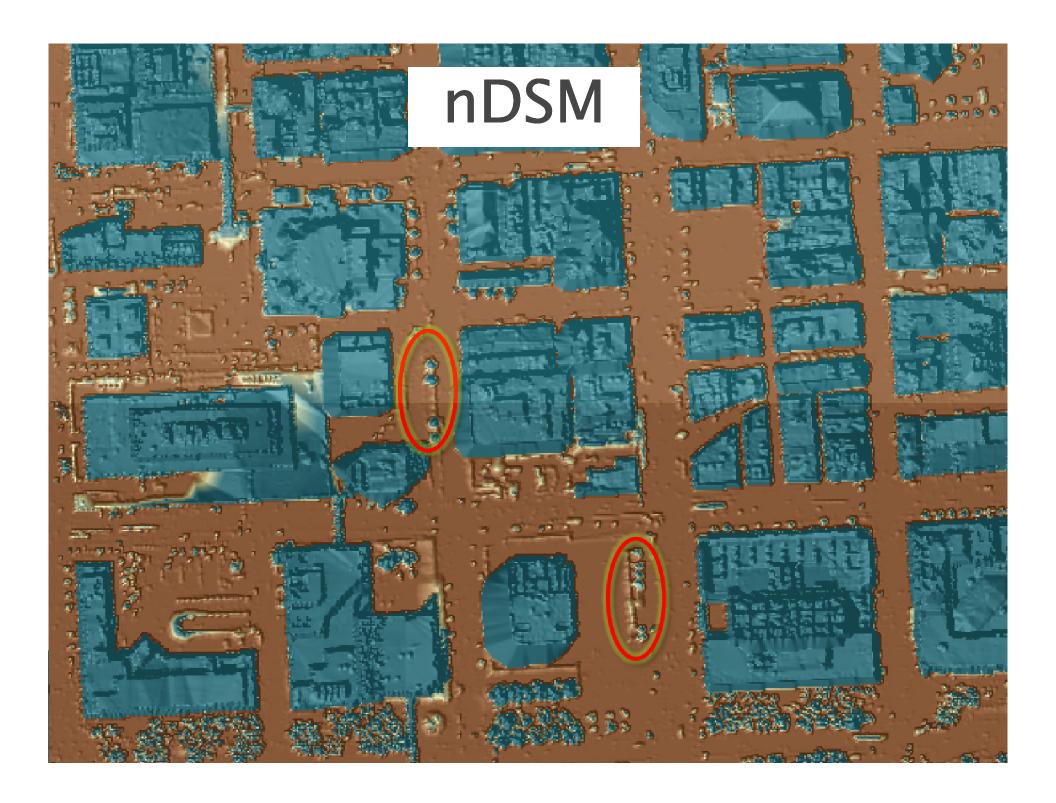


How valuable is that information?

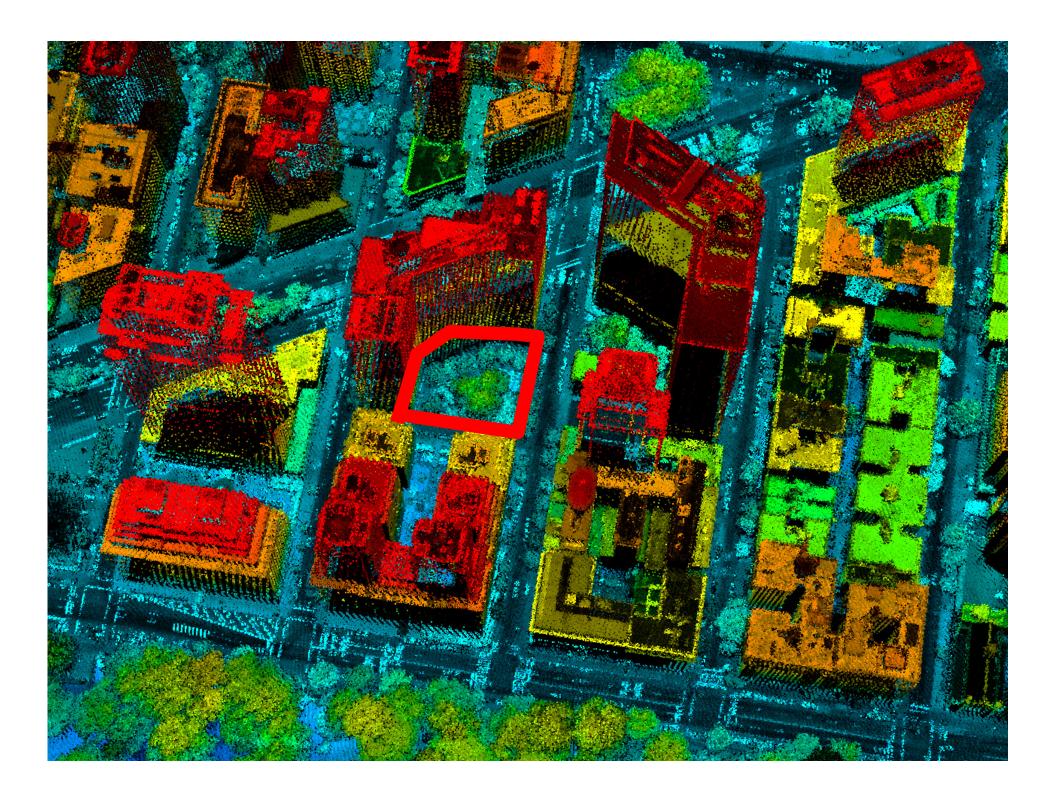


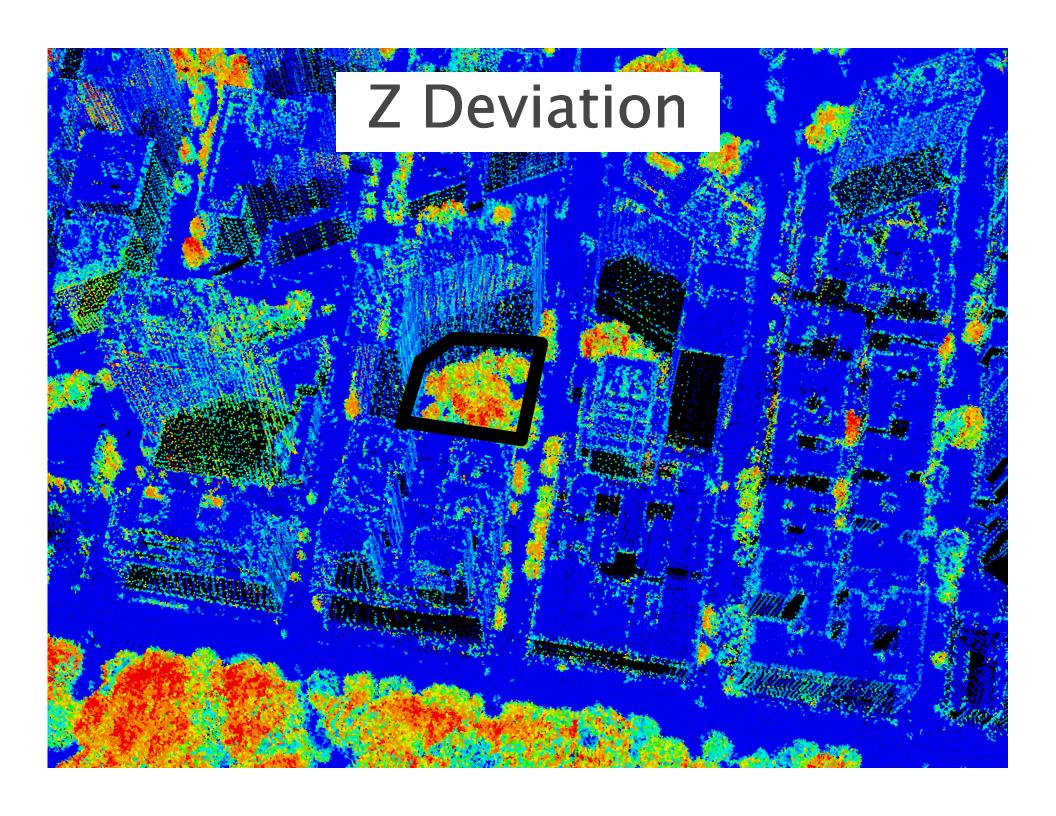




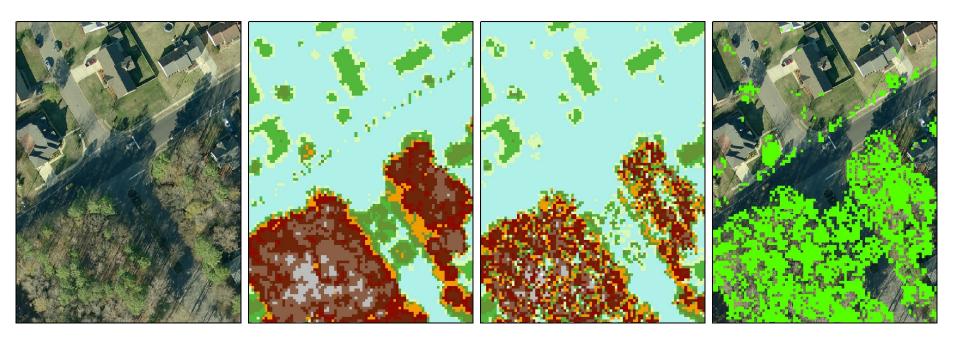








Simple Vegetation Mapping



First Return - Last Return = Vegetation



- More Complex Vegetation Mapping:
- Tree Canopy Rule Set:
 - High things (nDSM)
 - Multiple returns (mean # returns)
- False positives include:
 - Powerlines, some irregular rooftops, towers, awnings, decks, irregular structures
- Low vegetation (shrubs) and grass are difficult
- Leaf off collections not ideal.



- Impervious Surface Rule Set:
 - High or low (Buildings or pavement)
 - Single returns (mean # returns)
 - Not vegetation
 - Signal Intensity **
 - Variability
 - Resolution
- Imagery is higher resolution

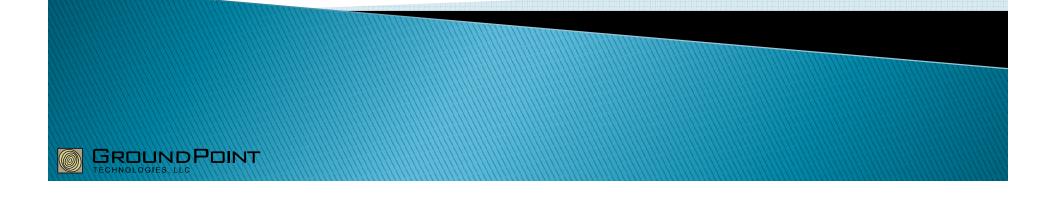


- Problems with Lidar Data
 - Raster data are from points
 - Statistical value of all points within a cell
 - Resolution is relatively coarse (~1m)
 - Interpolated values in NODATA cells (voids)
 - Context can be critical for feature ID
 - Image analysis can be critical
 - Higher resolution, Infrared

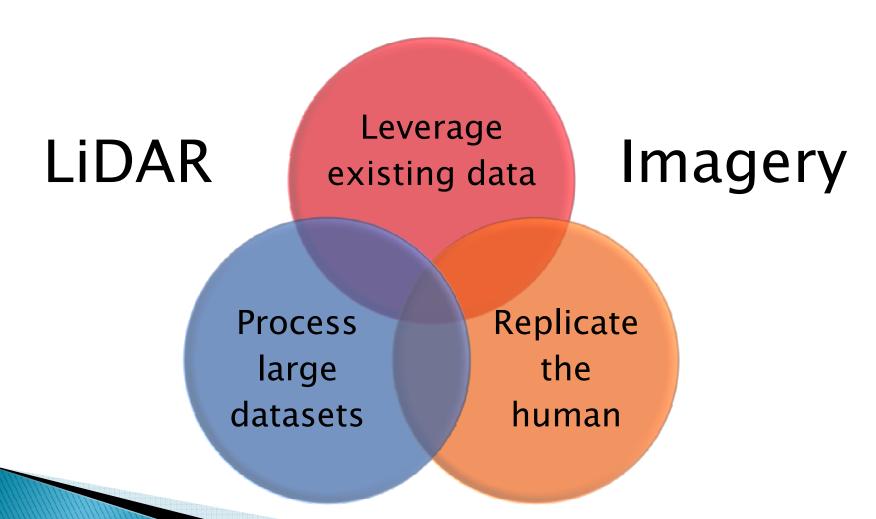


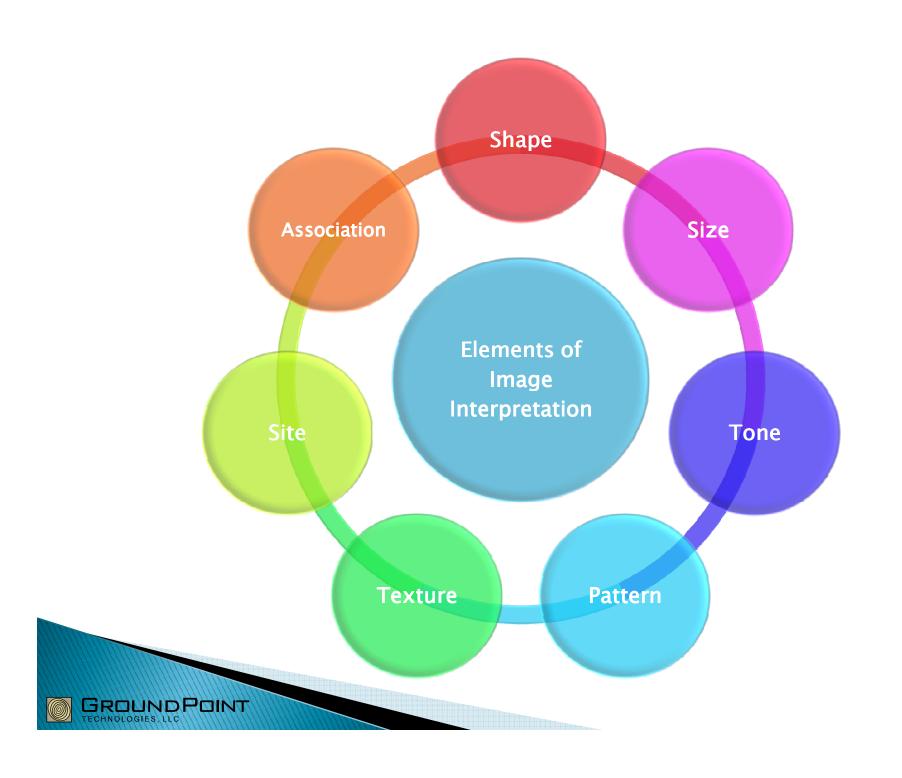
Even More Complex Analysis

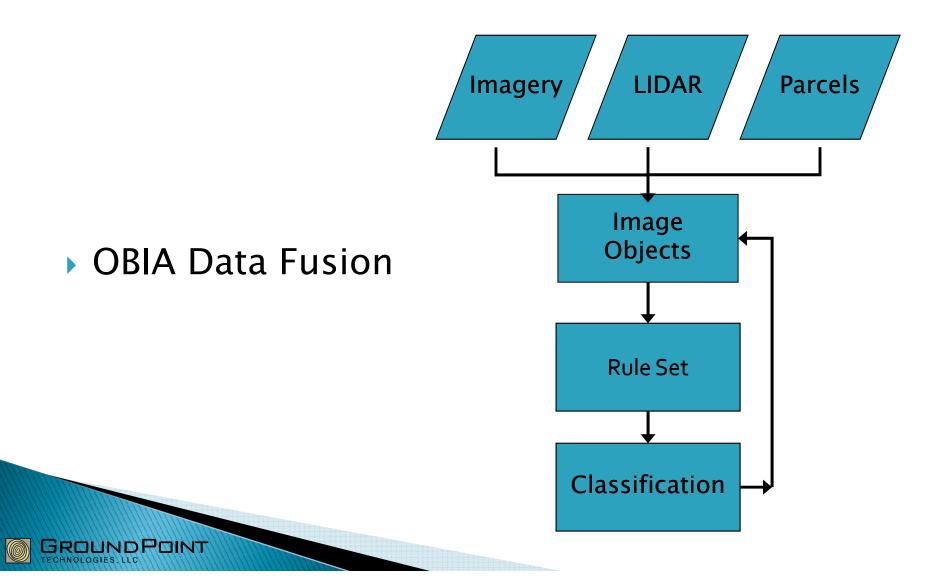
OBIA



Extracting Information Data Fusion







Rule Set

- What is a Rule Set?
 - A rule set is a set of Processing steps
 - It is stored in a Process Tree
- Rule Sets Define:
 - which Image Objects shall be processed with which Algorithm and under which Condition





Rule Set

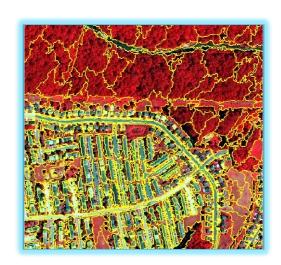
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Properties of Image Objects



- Color
 - → Mean, Ratio, Standard deviation
- Shape attributes
 - → Size, Length, rectangular fit
 - → long and skinny vs fat and round
- Texture attributes
 - → Smooth, rough
- Relations between objects & classes
 - → Mean difference to neighbors





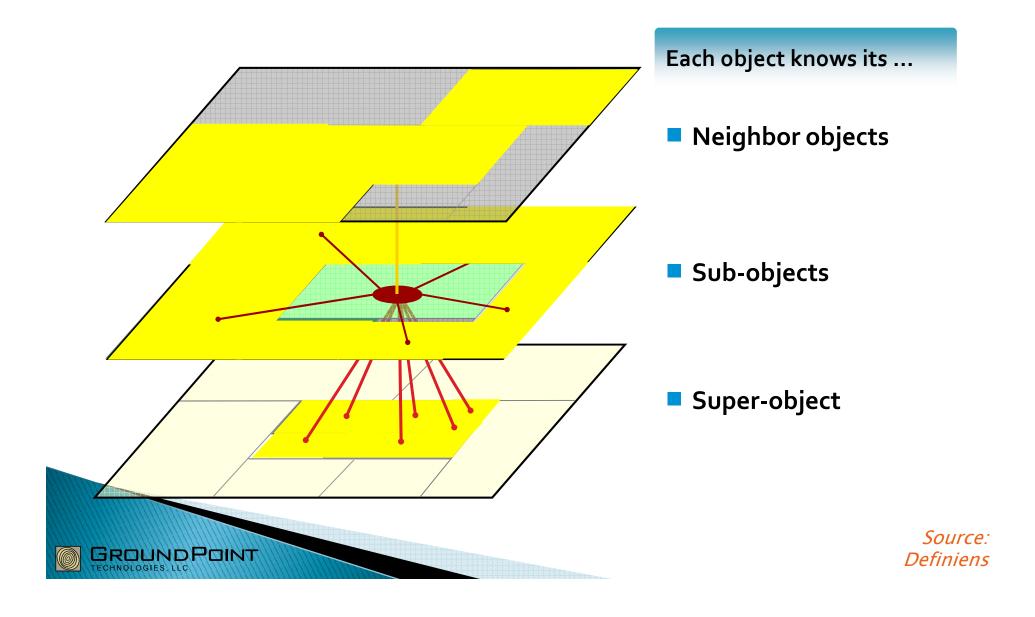




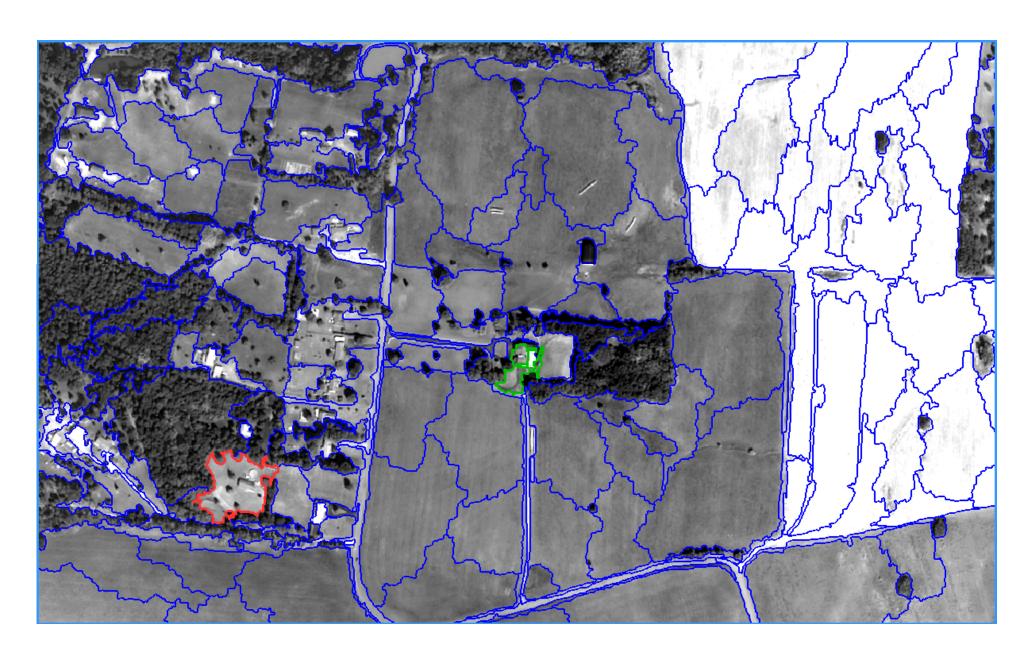




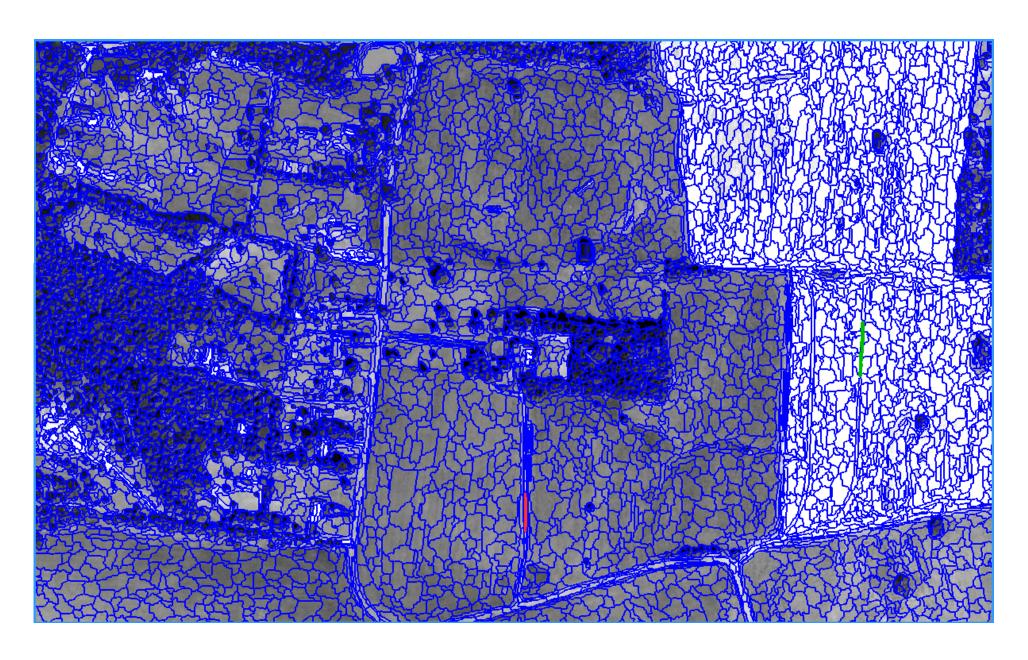
Network of Image Objects



Coarse Scale Segmentation



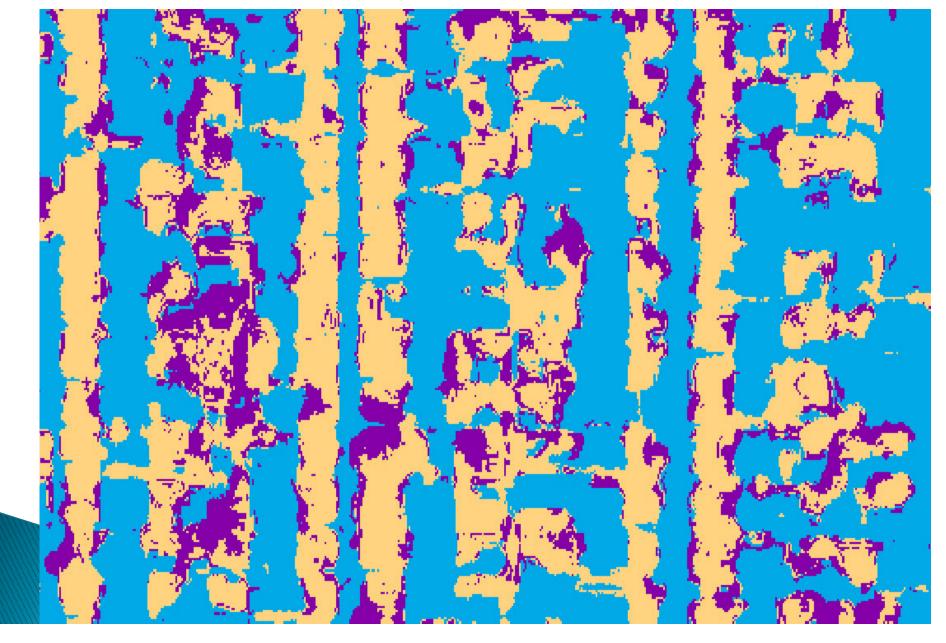
Fine Scale Segmentation



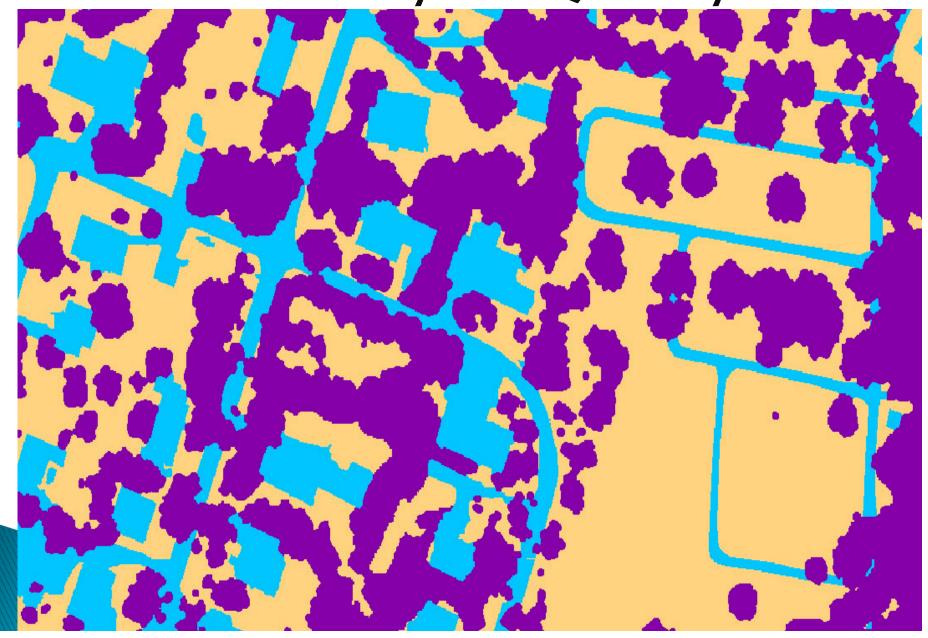




Accuracy vs Quality



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